

Topological Partitions of Euclidean Space by Spheres Author(s): Paul Bankston and Ralph Fox Source: *The American Mathematical Monthly*, Vol. 92, No. 6 (Jun. - Jul., 1985), pp. 423-424 Published by: <u>Mathematical Association of America</u> Stable URL: <u>http://www.jstor.org/stable/2322453</u> Accessed: 16/02/2011 12:47

Your use of the JSTOR archive indicates your acceptance of JSTOR's Terms and Conditions of Use, available at <a href="http://www.jstor.org/page/info/about/policies/terms.jsp">http://www.jstor.org/page/info/about/policies/terms.jsp</a>. JSTOR's Terms and Conditions of Use provides, in part, that unless you have obtained prior permission, you may not download an entire issue of a journal or multiple copies of articles, and you may use content in the JSTOR archive only for your personal, non-commercial use.

Please contact the publisher regarding any further use of this work. Publisher contact information may be obtained at http://www.jstor.org/action/showPublisher?publisherCode=maa.

Each copy of any part of a JSTOR transmission must contain the same copyright notice that appears on the screen or printed page of such transmission.

JSTOR is a not-for-profit service that helps scholars, researchers, and students discover, use, and build upon a wide range of content in a trusted digital archive. We use information technology and tools to increase productivity and facilitate new forms of scholarship. For more information about JSTOR, please contact support@jstor.org.



Mathematical Association of America is collaborating with JSTOR to digitize, preserve and extend access to The American Mathematical Monthly.

#### NOTES

sections on exact equations contain the standard test for exactness and often include a discussion of integrating factors, but I have seen none that develops a test for separability.

This paper gives a simply stated test for separability. In what follows D, the domain of f, is an open convex set in the plane, f is real valued, and partial derivatives of f are indicated by subscripts.

**PROPOSITION 1.** If there are differentiable functions  $\phi(x)$  and  $\psi(y)$  such that  $f(x, y) = \phi(x)\psi(y)$  for all  $(x, y) \in D$ , then  $f(x, y)f_{xy}(x, y) = f_x(x, y)f_y(x, y)$  for all  $(x, y) \in D$ .

The proof follows directly from  $f_x(x, y) = \phi'(x)\psi(y)$  and the corresponding formulas for the other partial derivatives.

**PROPOSITION 2.** If f,  $f_x$ ,  $f_y$  and  $f_{xy}$  are continuous in D, f(x, y) is never 0 in D, and  $f(x, y)f_{xy}(x, y) = f_x(x, y)f_y(x, y)$  for all  $(x, y) \in D$ , then there are continuously differentiable functions  $\phi(x)$  and  $\psi(y)$  such that  $f(x, y) = \phi(x)\psi(y)$  for all  $(x, y) \in D$ .

*Proof.* f has the same sign throughout D and factoring f is equivalent to factoring -f, so we may assume that f is positive on D. Now

$$\frac{\partial}{\partial y}\frac{f_x(x,y)}{f(x,y)} = \frac{f(x,y)f_{xy}(x,y) - f_x(x,y)f_y(x,y)}{f^2(x,y)} = 0.$$

Since  $\frac{\partial}{\partial x} \ln(f(x, y)) = f_x(x, y)/f(x, y)$ , we conclude that  $\frac{\partial}{\partial x} \ln(f(x, y))$  is a function of x alone and can write  $\frac{\partial}{\partial x} \ln(f(x, y)) = \alpha(x)$ . The function  $\alpha$  is continuous because f and  $f_x$  are.

Let  $\beta(x) = \int \alpha(x) dx$ . Then there is a function  $\gamma$  such that  $\ln(f(x, y)) = \beta(x) + \gamma(y)$ .  $\gamma$  is continuously differentiable because f and  $f_y$  are continuous.

Let  $\phi(x) = \exp(\beta(x))$  and  $\psi(y) = \exp(\gamma(y))$ . Then  $f(x, y) = \phi(x)\psi(y)$ , completing the proof.

As the following example shows, the condition that f is nonzero on D cannot be dropped. Define f(x, y) by

$$f(x, y) = \begin{cases} x^2 \exp(y), & \text{if } x \ge 0, \\ x^2 \exp(2y), & \text{if } x \le 0. \end{cases}$$

Direct computation shows that on  $\mathbb{R}^2$  we have  $ff_{xy} = f_x f_y$ . However f does not factor since if it did f(1, y), which is  $\exp(y)$ , and f(-1, y), which is  $\exp(2y)$ , would be proportional as functions of y.

One can replace the condition that f is nonzero on D by requiring that f(x, y) be an analytic function of x and y. Then, using Proposition 2 and the fact that if two analytic functions agree in a neighborhood of a point in D they agree on the connected set D, one can show that  $ff_{xy} = f_x f_y$  implies that f factors.

### TOPOLOGICAL PARTITIONS OF EUCLIDEAN SPACE BY SPHERES

# PAUL BANKSTON

Department of Mathematics, Statistics and Computer Science, Marquette University, Milwaukee, WI 53233

## RALPH FOX

Department of Mathematics, George Mason University, Fairfax, VA 22030

A space X partitions a space Y if there is a family of topological embeddings of X into Y whose images form a cover of Y by pairwise disjoint sets. In [1] (whose notation and terminology we follow here) it is shown that the *n*-sphere S(n) cannot partition euclidean (n + 1)-space  $\mathbb{R}^{n+1}$  (an easy result) and that if X is any nonempty subspace of S(n), then X partitions  $\mathbb{R}^{2n+1}$ . An obvious question then arises as to whether S(n) partitions  $\mathbb{R}^m$  for n + 1 < m < 2n + 1 (Ques-

tion 3.1 (iv) of [1]). In this note we give an affirmative answer based on an unpublished construction due to S. Kakutani and communicated to us by P. R. Halmos [4] (who learned of the construction forty years ago). This construction, used to give a partition of  $\mathbb{R}^3$  by S(1), is extremely simple, essentially different from those given in [1], and easily generalizable. Because several people have looked at the problem since the completion of [1], we thought the solution should be publicized as a short postscript to that paper.

**THEOREM.** S(n) partitions  $\mathbb{R}^{n+2}$  in such a way that each sphere is tamely embedded, unknotted, and not linked with any other member of the partition.

*Proof.* We partition  $\mathbb{R}^{n+2}$  into *n*-spheres as follows: First let  $C_1$  be an open unbounded cylinder in  $\mathbb{R}^{n+2}$ . To be specific, we let  $X_1$  be a coordinate axis in  $\mathbb{R}^{n+1}$  and let  $C_1$  be the product of  $X_1$  with the open unit ball in the (n + 1)-dimensional vector subspace perpendicular to  $X_1$ . Now  $\mathbb{R}^{n+2} \setminus C_1$ , being homeomorphic with  $\mathbb{R}^1 \times [1, \infty) \times S(n)$ , is easily partitioned into spheres; and  $C_1$  is homeomorphic with  $\mathbb{R}^{n+2}$ .

Let  $C_2$  be an open unbounded cylinder in  $C_1$  formed in a U-shape—i.e., let  $R_1, R_2$  be parallel translates of a closed ray in  $X_1$ , let L be the straight line segment joining the endpoints of  $R_1, R_2$ , and let  $C_2$  be the interior of a regular thickening of  $R_1 \cup L \cup R_2$ . We then choose a branch of  $C_2$ and form another open unbounded U-shape  $C_3$  in exactly the same fashion, making sure that the base of  $C_3$  is at least a unit distance from the base of  $C_2$ . Proceed inductively. For each  $n \ge 1$ ,  $C_n$ is homeomorphic with  $\mathbb{R}^{n+2}$ , and  $C_n \setminus C_{n+1}$  is homeomorphic with  $\mathbb{R}^1 \times [1, \infty) \times S(n)$ . Finally, because the U-shapes are pushed unboundedly far from the origin, it is easy to see that  $\bigcap_{n=1}^{\infty} C_n = \emptyset$ . This completes the construction. (It is obvious that there is no linking or knotting, and each sphere is tamely embedded.)  $\square$ 

The following question now becomes inevitable.

Revised Question 3.1 (iv) [1]: Is there a nonempty subspace of S(2) which does not partition  $\mathbb{R}^4$ ? Of course by the above we now need only look in  $\mathbb{R}^2 \subseteq S(2)$  for candidates, but this brings us to the question of whether in general there are nonempty subsets of  $\mathbb{R}^n$  which do not partition  $\mathbb{R}^{n+1}$  This is basically Question 3.1 (ii) in [1], and we are little closer to a solution now than we were when the issue first arose.

REMARK. In [5], A. Szulkin offers a new solution to the problem of whether S(1) partitions  $\mathbb{R}^3$ , in response to a re-posing of the question by H. S. Shapiro. (Problems like this have a way of surfacing time and again. See also [2] and [3] for similar problems.) So far, we know of four distinct solutions, each with its own particular merits. To comment:

(i) Of the two solutions offered in [1], one of them uses the Axiom of Choice. While the constructive solution is more visual, the Jordan curves in the partition are quite general. However, in the nonconstructive solution, all of the Jordan curves can be taken to be standard circles (of equal radius). Neither solution generalizes to higher dimensions.

(ii) Szulkin's solution combines the attractive features of both of the solutions in [1]; namely it constructively partitions  $\mathbb{R}^3$  into circles (whose radii include all positive real numbers). However, it too fails to generalize to higher dimensions.

(iii) While the Kakutani solution (as well as the above generalization) is constructive, it involves highly noncircular Jordan curves. This, of course, prompts the question of whether  $\mathbb{R}^{n+2}$  can always be partitioned into standard *n*-spheres.

## References

1. P. Bankston and R. McGovern, Topological partitions, General Topology and Appl., 10 (1979) 215–229, MR#80i:54007.

2. \_\_\_\_\_, On partitions of plane sets into simple closed curves, Proc. Amer. Math. Soc., 88 (1983) 691-697.

3. \_\_\_\_\_, On partitions of plane sets into simple closed curves, II, Proc. Amer. Math. Soc., 89 (1983) 498-502.

4. P. R. Halmos (private communication).

5. A. Szulkin,  $\mathbb{R}^3$  is the union of disjoint circles, this MONTHLY, 90 (1983) 640–641.